

TOF Principle



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| Sensing principle | TOF |
| Laser wavelength | 905 nm |
| Max. Sensing range | 10 m (70% reflectivity)/4 m (10% reflectivity) |
| Scanning angle range | 270° |
| Sampling frequency | 18 KHz / 54 KHz |
| Scanning frequency | 25 Hz |
| Resolution | 0.5° |
| Measuring accuracy | ± 2 cm (within the range of 10 m) |
| Response time | 40 ms |
| Startup relay | < 10 s |
| Channels | 64 channels (each channel contains 3 detected areas) |
| Detection output delay | 0 – 2 s , adjustable |
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| Detected size | 0 – 5° , size |
| Switch input | Quantity: 6 (NPN) |
| Switch output | Quantity: 4 (3 for area signal, 1 for warning) |
| Indicator | Quantity: 4 (3 for area signal, 1 for warning) |
| Communication interface | USB-TYPE C (serial port) |
| Operating voltage | DC 9 V – 28 V |
| Power consumption | Power Rating: < 1 W (no load) Starting power: < 3 W (no load) |
| Working temperature | -10 °C to 50 °C |
| Storage temperature | -20 °C to 70 °C |
| Humidity | Less than 85%, non-condensing |
| Protection degree | IP65 |
| Ambient brightness | 80000 Lux |
| Weight | 171 g |
| Size | 50 mm(L) * 50 mm(W) * 72 mm(H) |
| Model | AS-33C |

LiDAR Scanner

Specification

Unit: mm

